

# COP 4600 – Summer 2011

## Introduction To Operating Systems

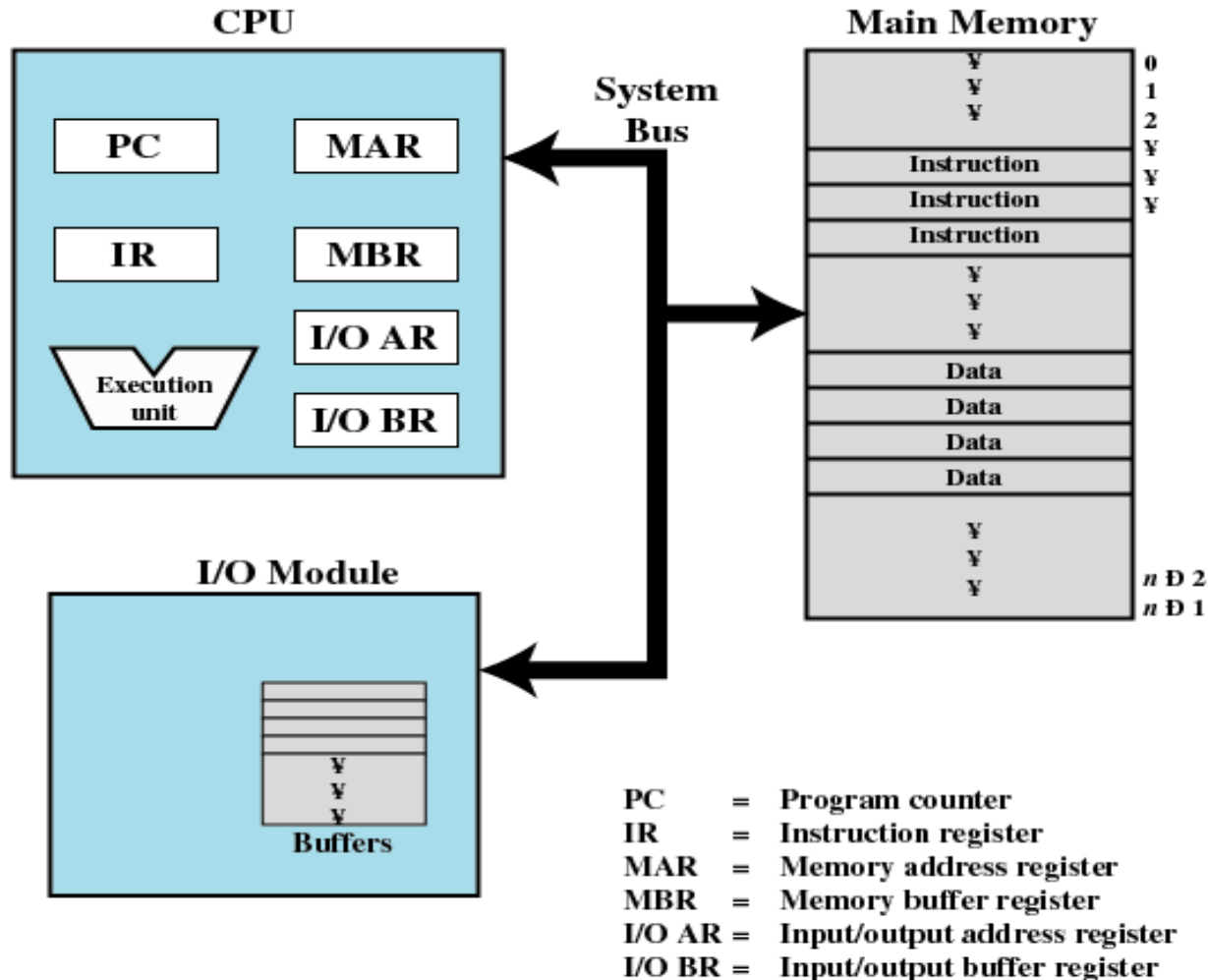
### Hardware Considerations For OS

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# Top-Level Computer Components



# Processor Registers

- User-visible registers
  - Enable programmer to minimize main-memory references by optimizing register use
- Control and status registers
  - Used by processor to control operating of the processor
  - Used by privileged operating-system routines to control the execution of programs



# User-Visible Registers

- May be referenced by machine language
- Available to all programs - application programs and system programs
- Types of registers
  - Data
  - Address
    - Index
    - Segment pointer
    - Stack pointer



# User-Visible Registers

- Address Registers
  - Index
    - Involves adding an index to a base value to get an address
  - Segment pointer
    - When memory is divided into segments, memory is referenced by a segment and an offset
  - Stack pointer
    - Points to top of stack



# Control and Status Registers

- Program Counter (PC)
  - Contains the address of an instruction to be fetched
- Instruction Register (IR)
  - Contains the instruction most recently fetched
- Program Status Word (PSW)
  - Condition codes
  - Interrupt enable/disable
  - Supervisor/user mode



# Control and Status Registers

- Condition Codes or Flags
  - Bits set by the processor hardware as a result of operations
  - Examples
    - Positive result
    - Negative result
    - Zero
    - Overflow



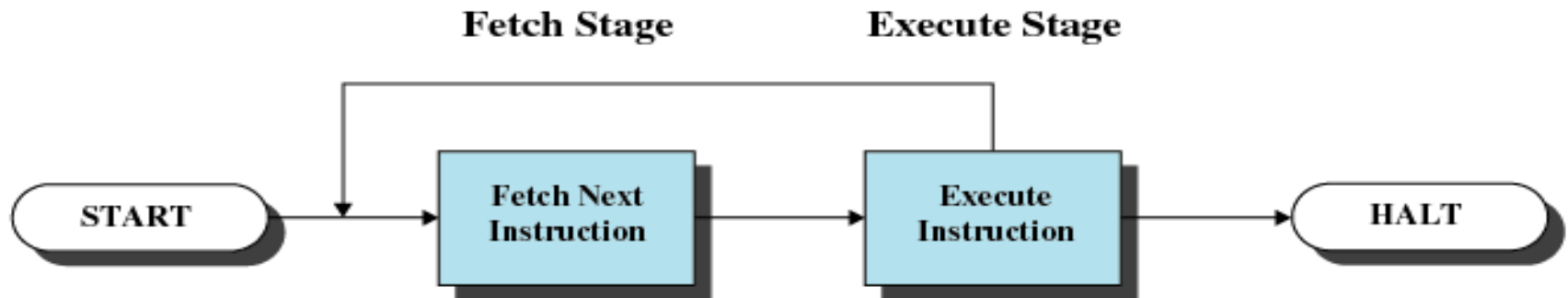
# Instruction Execution

- Two steps (Fetch/Decode & Execute)
  - Processor reads instructions from memory
    - Fetches into the MBR (MDR)
  - Processor executes each instruction





# Instruction Cycle



# Instruction Fetch and Execute

- The processor fetches the instruction from memory
- Program counter (PC) holds address of the instruction to be fetched next
- Program counter is incremented after each fetch

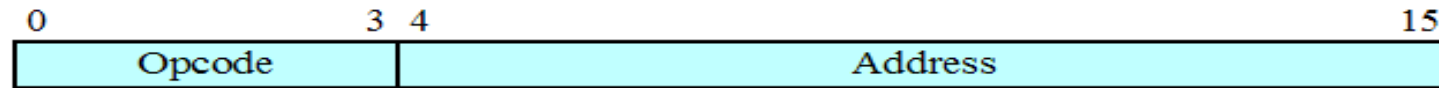


# Instruction Register

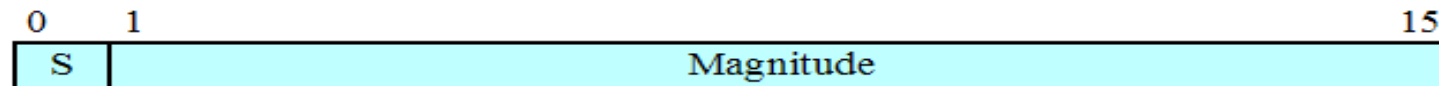
- Fetched instruction is placed in the instruction register
- Categories
  - Processor-memory
    - Transfer data between processor and memory
  - Processor-I/O
    - Data transferred to or from a peripheral device
  - Data processing
    - Arithmetic or logic operation on data
  - Control
    - Alter sequence of execution



# A Hypothetical Machine



**Instruction format**



**Integer format**

16-bit word = 4 bytes

Program Counter (PC) = Address of instruction  
Instruction Register (IR) = Instruction being executed  
Accumulator (AC) = Temporary storage

## **Internal CPU registers**

0001 = Load AC from Memory  
0010 = Store AC to Memory  
0101 = Add to AC from Memory

Instructions are 4 bits = 1 byte = 1 hexadecimal digit

## **Partial list of opcodes**



# An Aside on Number Systems

Binary = base 2, digits are 0, 1

Decimal = base 10, digits are 0,1,2,3,4,5,6,7,8,9

Hexadecimal = base 16, digits are 0,1,2,3,4,5,6,7,8,9,A,B,C,D,E,F

1 **binary digit** = 1 bit. 1 bit can represent either 0 or 1 (e.g. on or off)

Positional notation is represented via digit position as a power of 2.

$$(x + 2^n) + \dots + 2^5 + 2^4 + 2^3 + 2^2 + 2^1 + 2^0 \text{ (recall that } x^0 = 1 \text{ and } 0^x = 0)$$

So, 2 bits can represent up to base 4 (digits 0,1,2,3), since

$$(0 + 2^1) + (0 + 2^0) = 0$$

$$(0 + 2^1) + (1 + 2^0) = 1$$

$$(1 + 2^1) + (0 + 2^0) = 2$$

$$(1 + 2^1) + (1 + 2^0) = 3$$



# An Aside on Number Systems

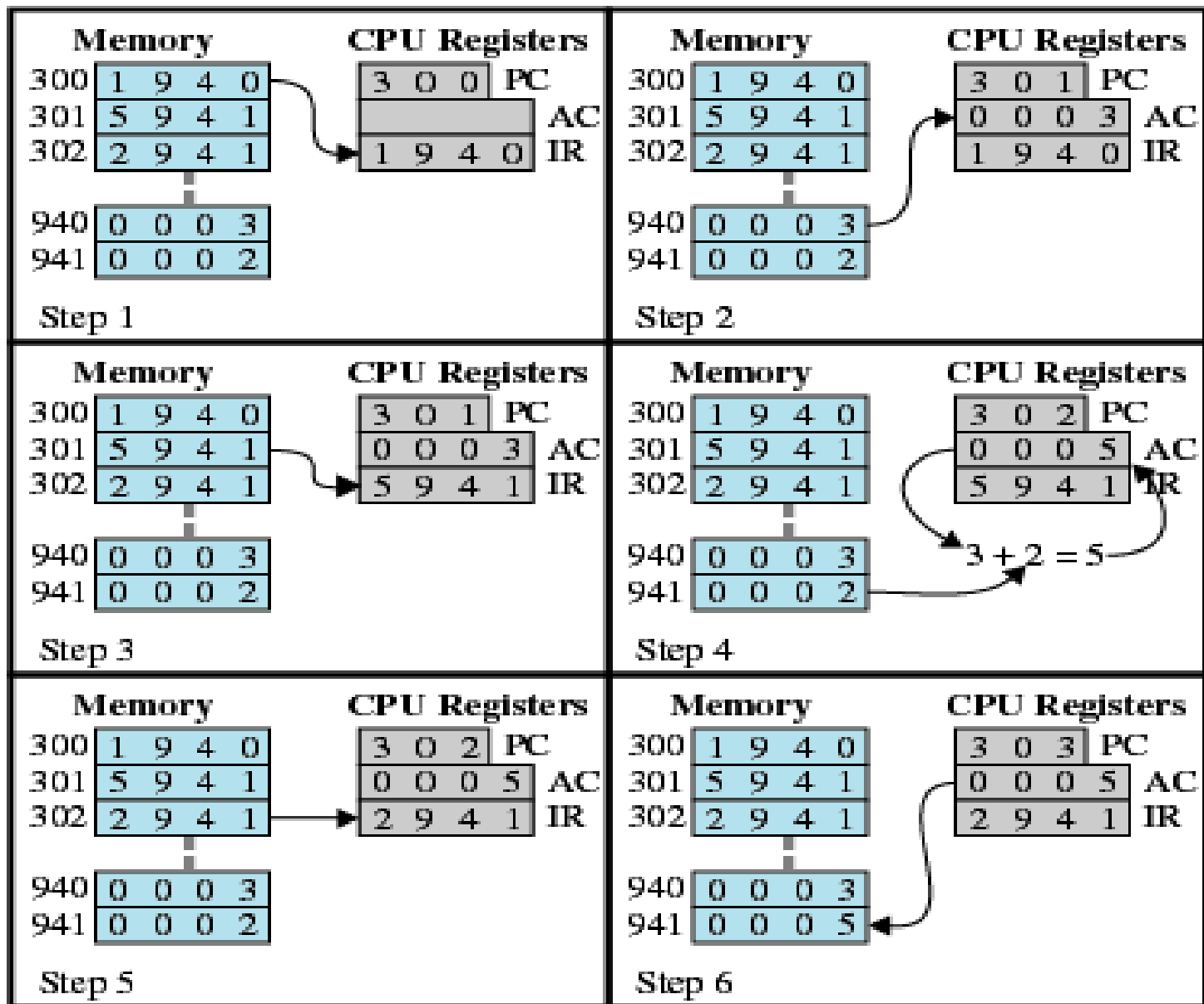
HEX	DECIMAL	OCTAL	BINARY
0	0	0	0000
1	1	1	0001
2	2	2	0010
3	3	3	0011
4	4	4	0100
5	5	5	0101
6	6	6	0110
7	7	7	0111
8	8	10	1000
9	9	11	1001
A	10	12	1010
B	11	13	1011
C	12	14	1100
D	13	15	1101
E	14	16	1110
F	15	17	1111

For hexadecimal, 4 bits are required to represent 1 hex digit.

The hex number 345 in binary would be written as 1101000101 (leading zeros are dropped).

$$\begin{array}{cccccccc} 1 & 1 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 1 \\ \underbrace{\hspace{1.5cm}} & \underbrace{\hspace{1.5cm}} & \underbrace{\hspace{1.5cm}} & & & & & & & \\ = 3_{16} & = 4_{16} & = 5_{16} & & & & & & & \end{array}$$





# Explanation of Example Program Execution

1. The PC contains 300, the address of the first instruction. This instruction (with value 1940 in hexadecimal) is loaded into the instruction register (IR) and the program counter (PC) is incremented. Note that both the MAR and MDR are used in this step but are not shown in the previous slide.
2. The first 4 bits (first hex digit) in the IR indicates that the accumulator register (AC) is to be loaded from memory. Decode of opcode indicates 0001 which represents the load accumulator from memory instruction. The remaining 12 bits (3 hex digits) represents the memory address where the operand (the value to be loaded into the accumulator) is located. This address is 940 (also in hex).





# Explanation of Example Program Execution

3. The next instruction (hex 5941), is fetched from memory location 301 and the PC is incremented. The decode of this instruction indicates an instruction (opcode 0101) that adds the value in the AC to a value obtained from the memory location specified in the operand of the instruction as (hex 941).
4. The old contents of the AC and the contents of memory location 941 are added together and the result is stored in the AC.
5. The next instruction (hex 2941), is fetched from memory location 302 and the PC is incremented. The decode of this instruction indicates an instruction (opcode 0010) that stores the contents of the AC into the memory location specified in the operand of the instruction as (hex 941).
6. The contents of the AC are stored in memory location 941.



# Interrupts

- Interrupt the normal sequencing of the processor
- Most I/O devices are slower than the processor
  - Processor must pause to wait for device

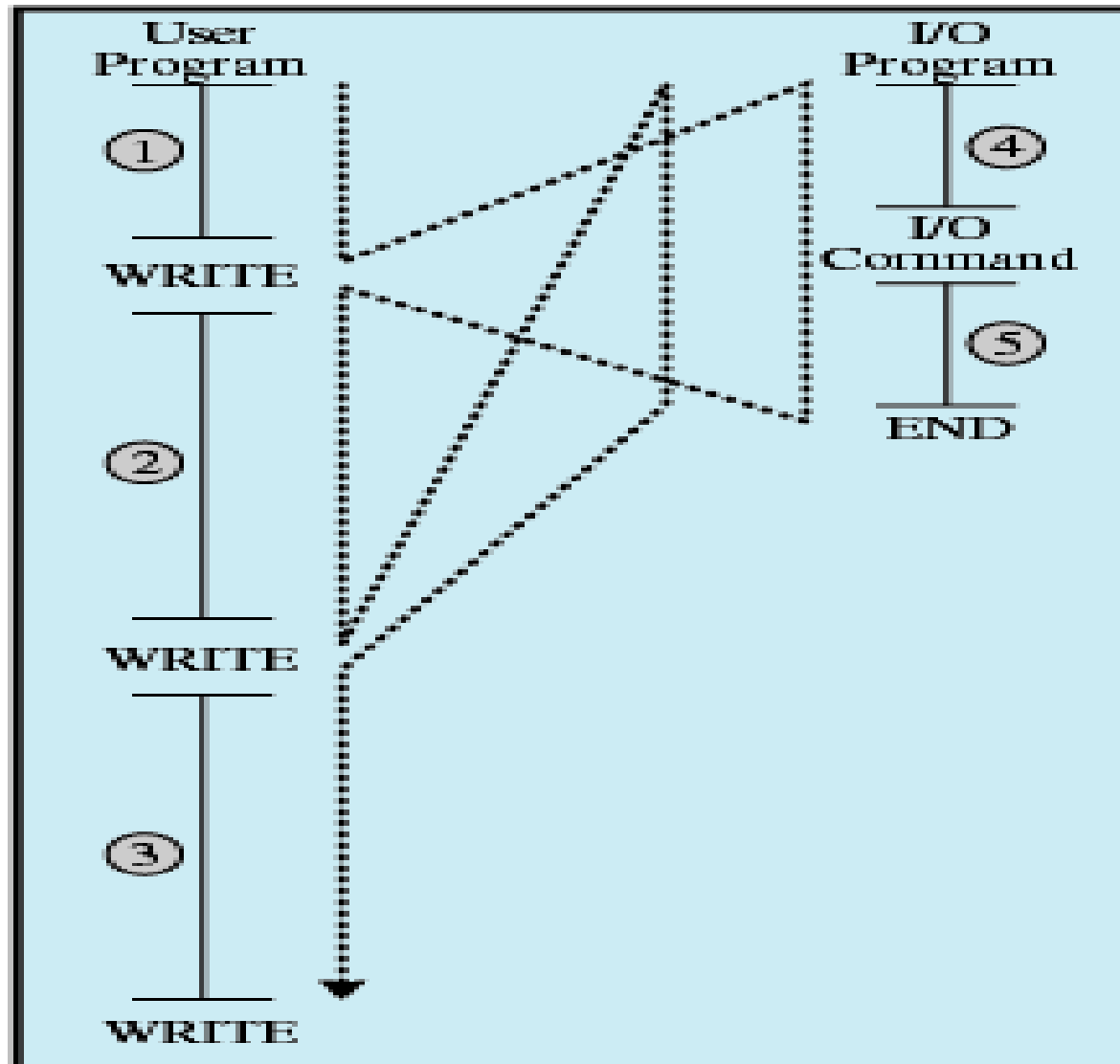


# Classes of Interrupts

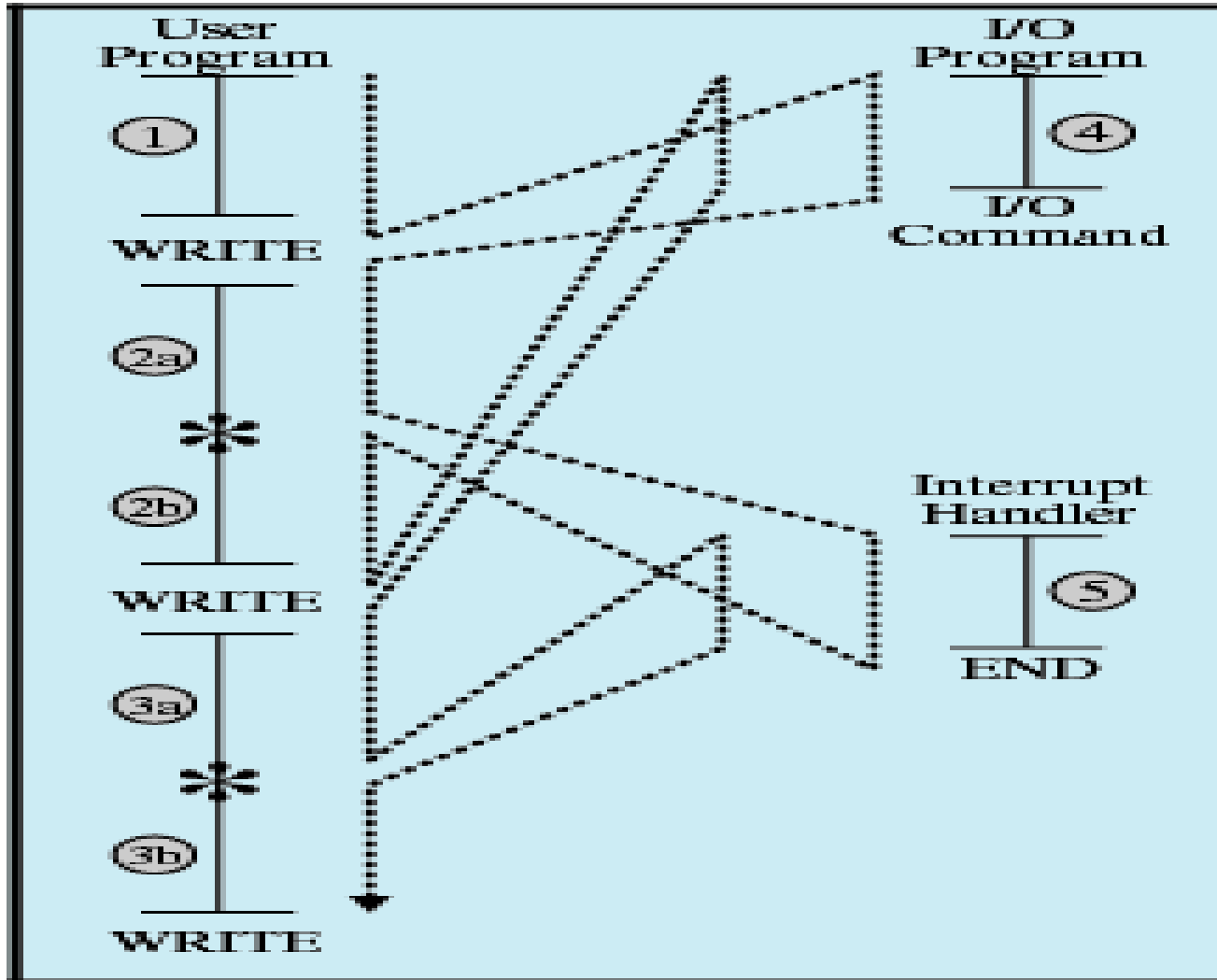
<b>Program</b>	Generated by some condition that occurs as a result of an instruction execution, such as arithmetic overflow, division by zero, attempt to execute an illegal machine instruction, and reference outside a user's allowed memory space.
<b>Timer</b>	Generated by a timer within the processor. This allows the operating system to perform certain functions on a regular basis.
<b>I/O</b>	Generated by an I/O controller, to signal normal completion of an operation or to signal a variety of error conditions.
<b>Hardware failure</b>	Generated by a failure, such as power failure or memory parity error.



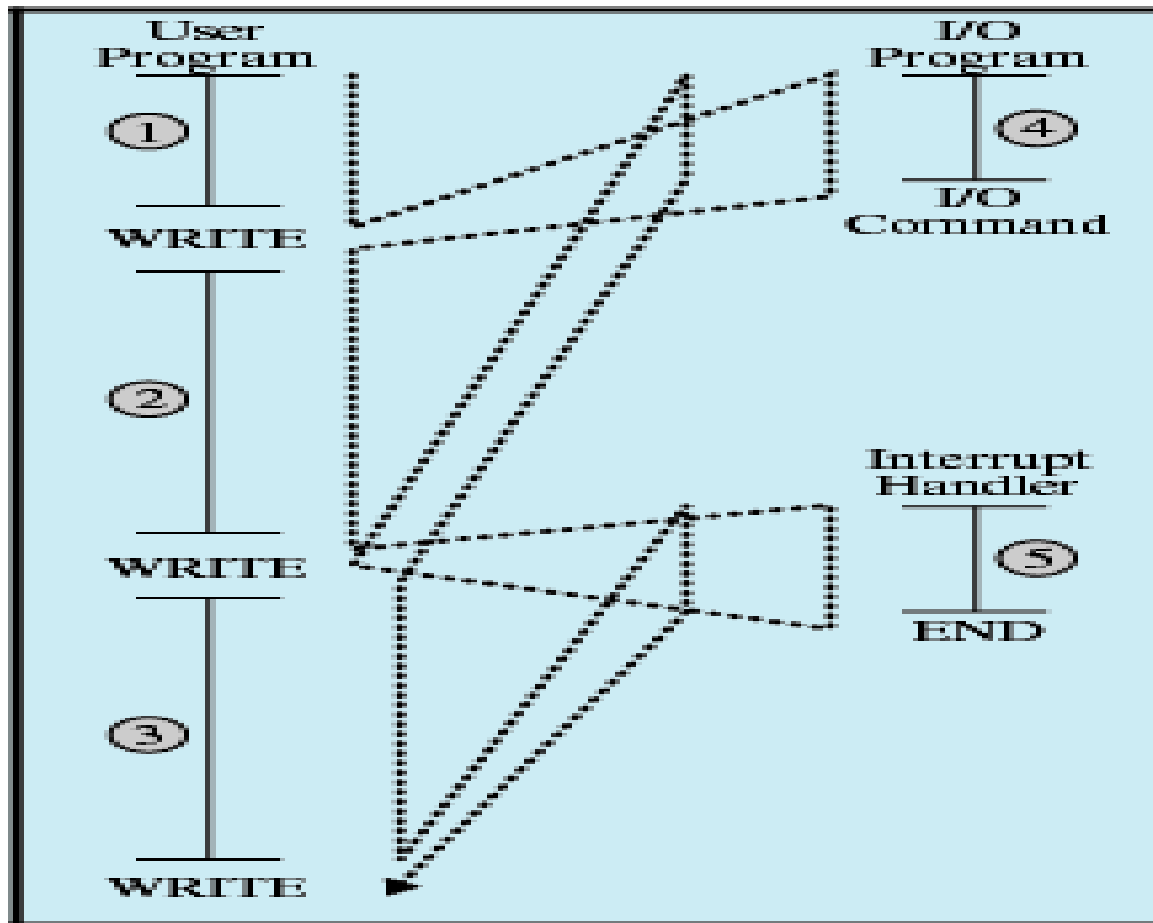
# Program Flow of Control Without Interrupts



# Program Flow of Control With Interrupts, Short I/O Wait



# Program Flow of Control With Interrupts; Long I/O Wait



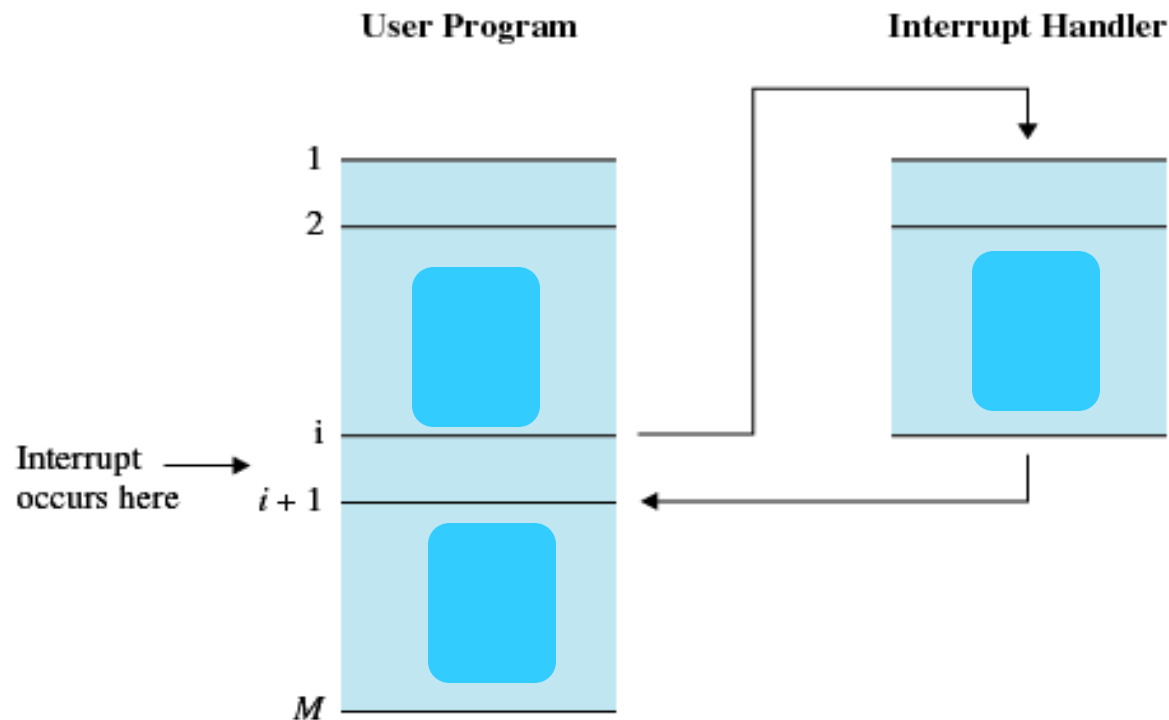
# Interrupt Handler

- Program to service a particular I/O device
- Generally part of the operating system



# Interrupts

- Suspends the normal sequence of execution

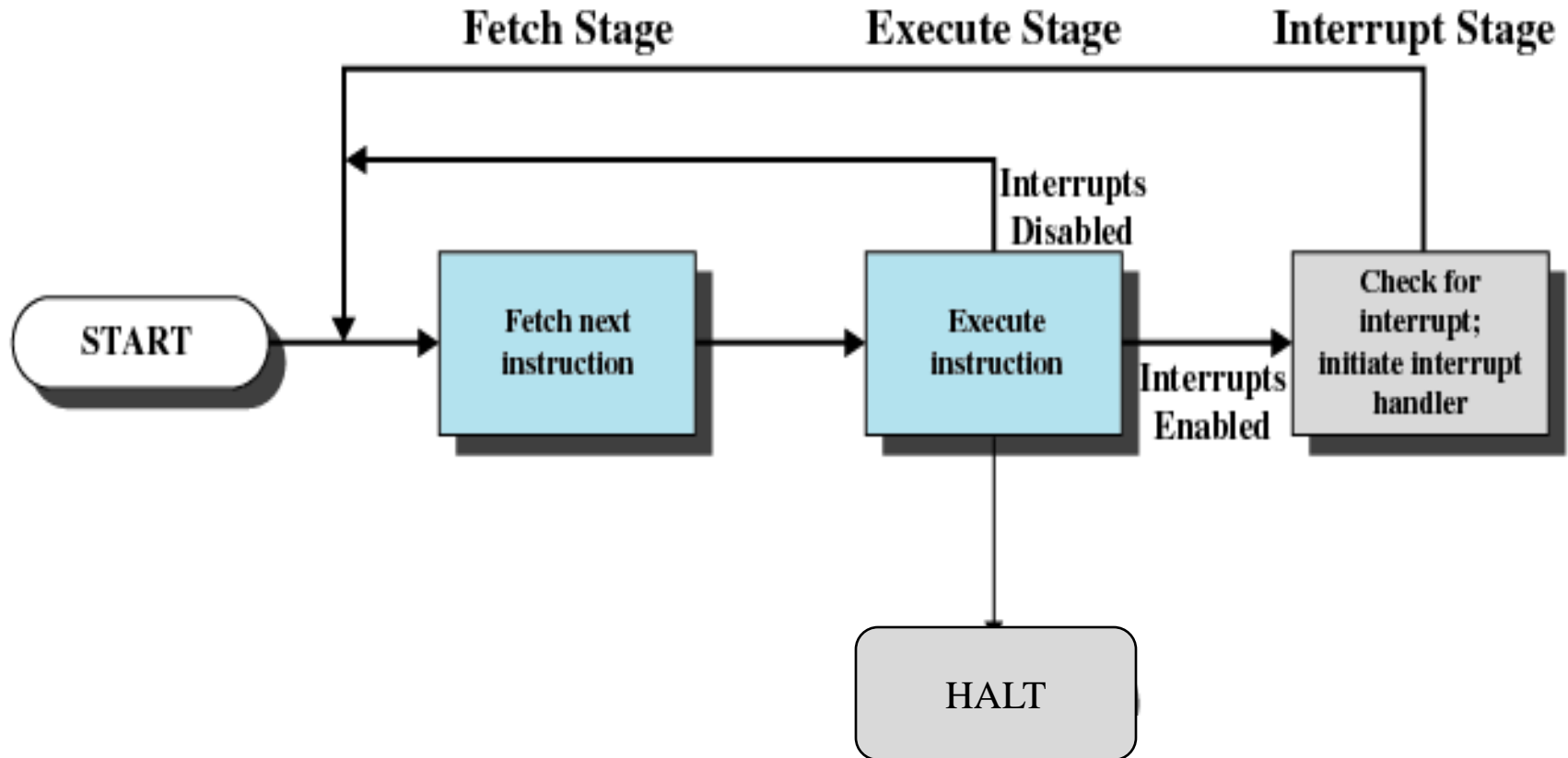


**Fig**





# Interrupt Cycle

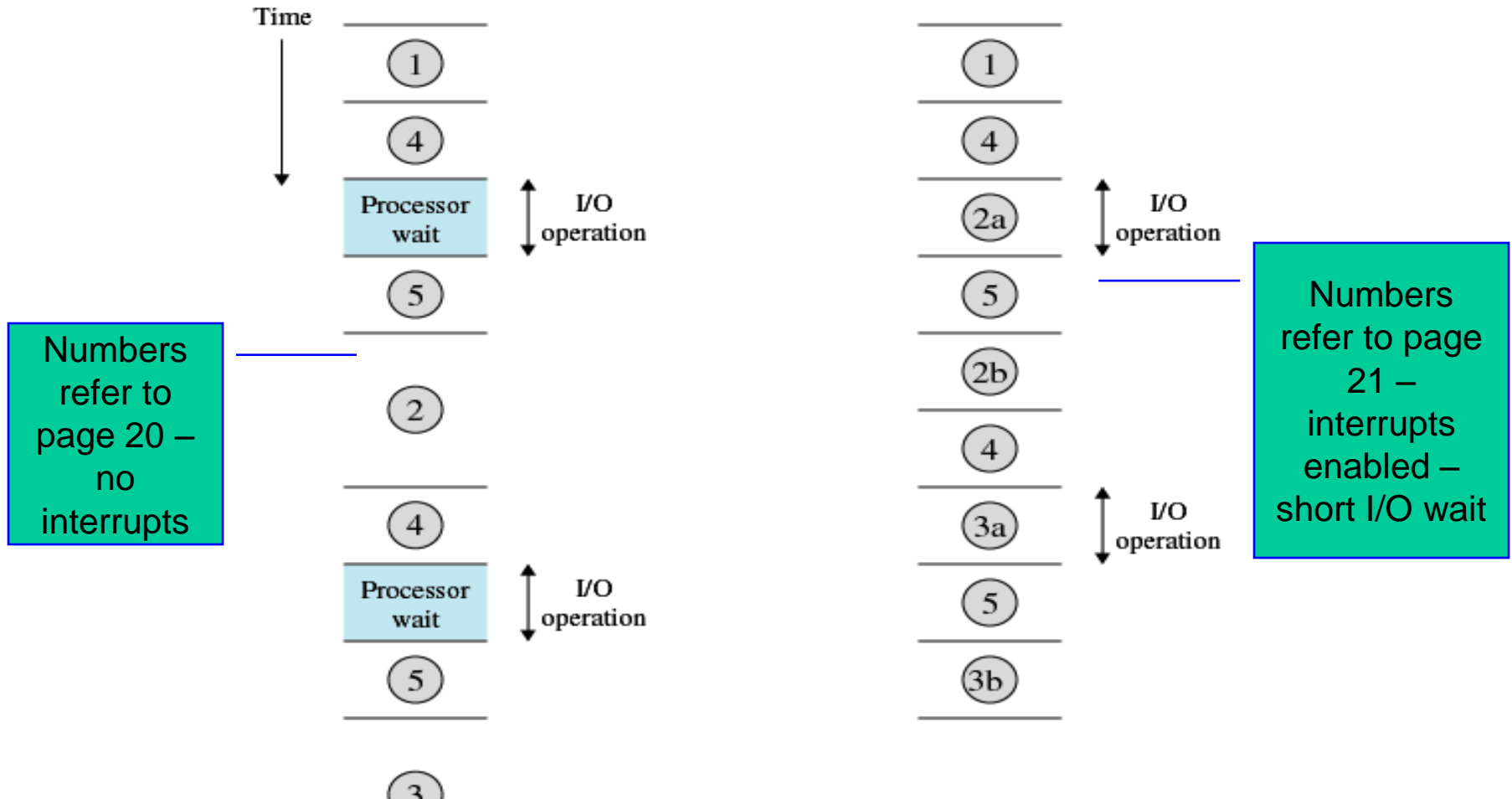


# Interrupt Cycle

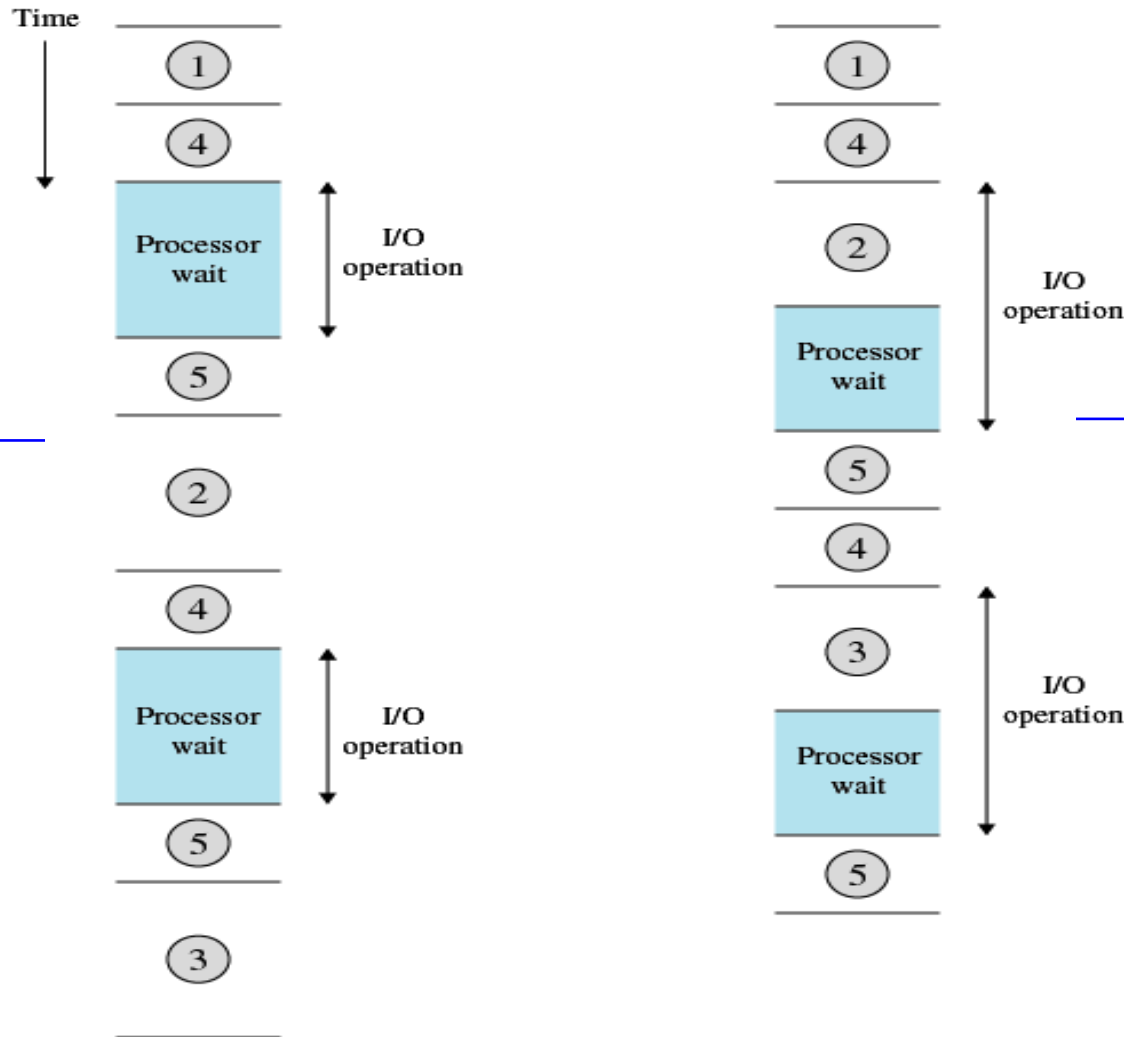
- Processor checks for interrupts
- If no interrupts fetch the next instruction for the current program
- If an interrupt is pending, suspend execution of the current program, and execute the interrupt-handler routine



# Timing Diagram Based on Short I/O Wait



# Timing Diagram Based on Long I/O Wait

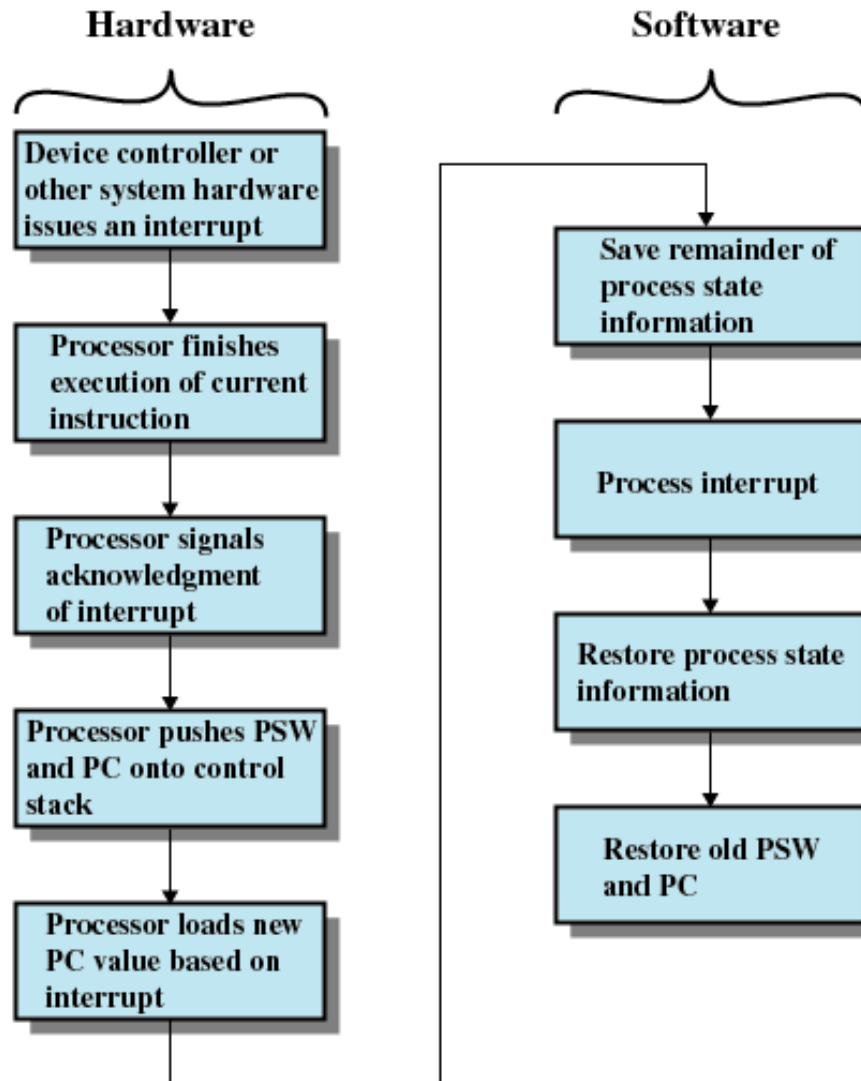


Numbers  
refer to  
page 20 –  
no  
interrupts

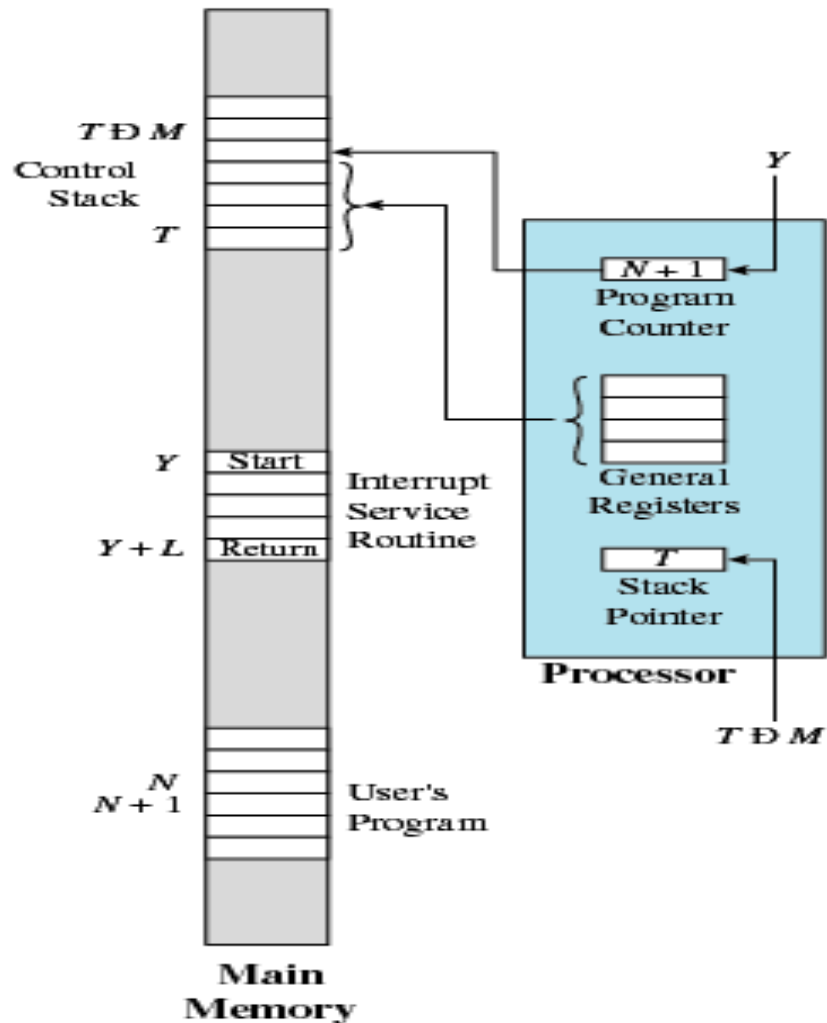
Numbers  
refer to  
page 22 –  
interrupts  
enabled  
with long  
I/O wait



# Simple Interrupt Processing



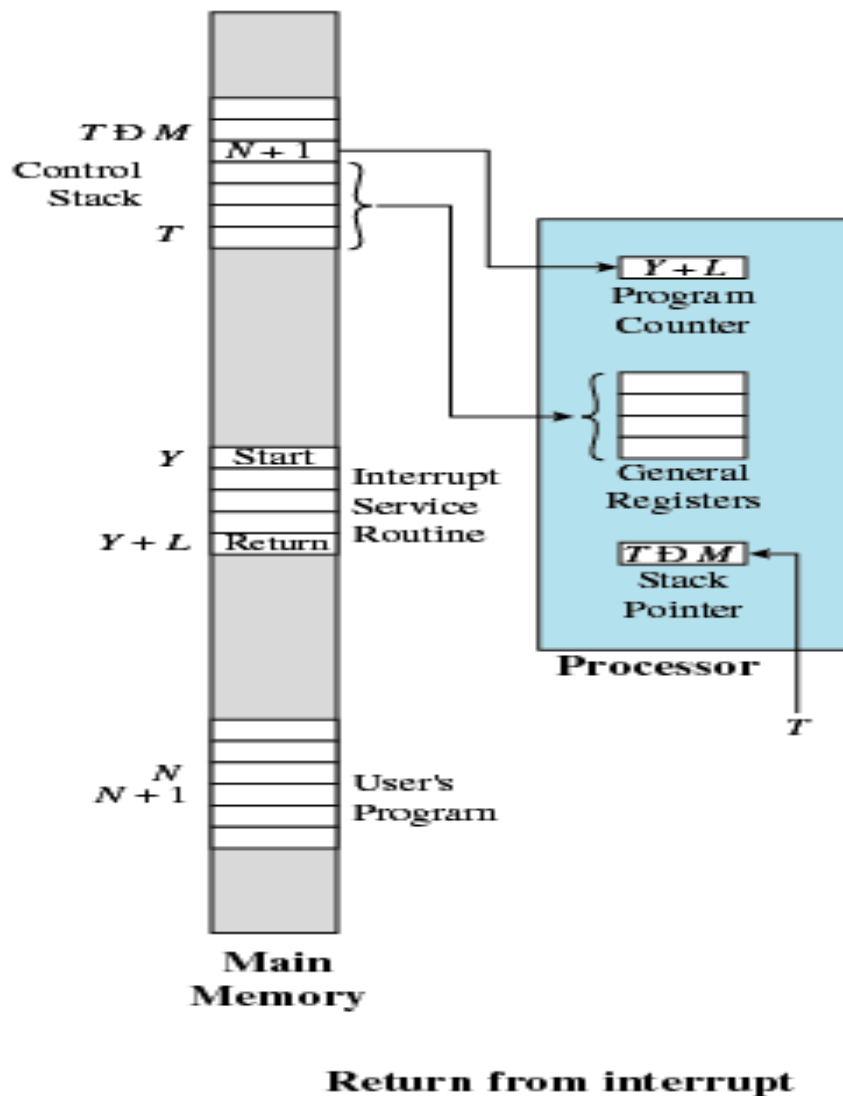
# Changes in Memory and Registers for an Interrupt



**Interrupt occurs after instruction at location  $N$**

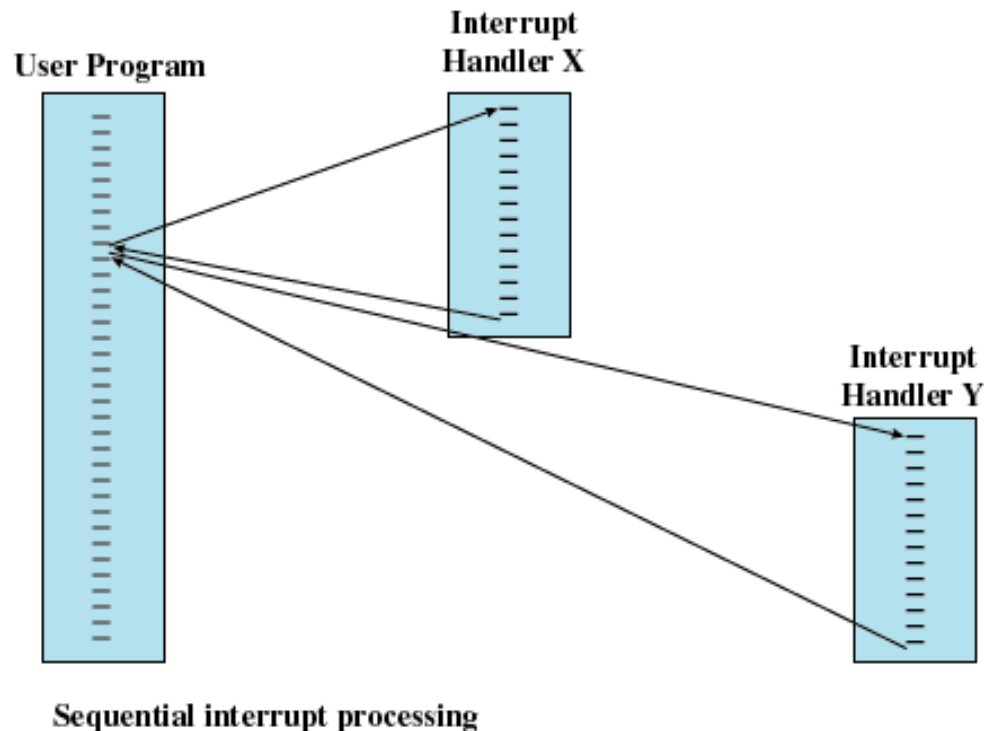


# Changes in Memory and Registers for an Interrupt



# Multiple Interrupts

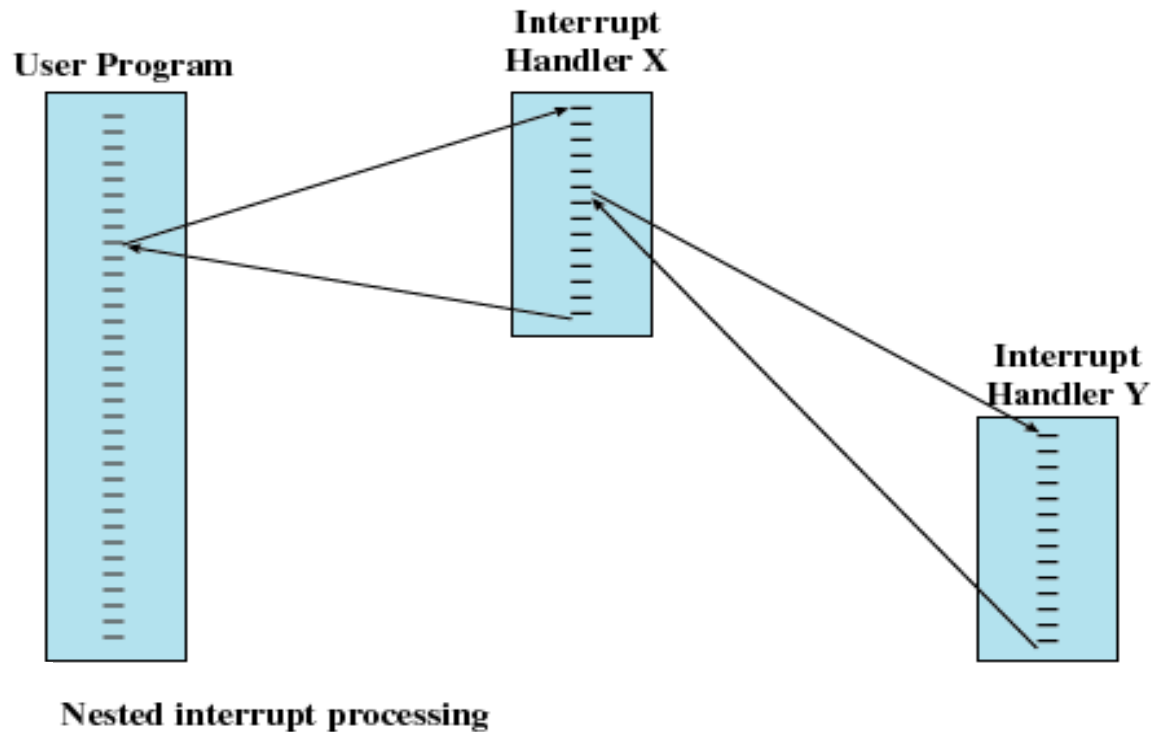
- Disable interrupts while an interrupt is being processed



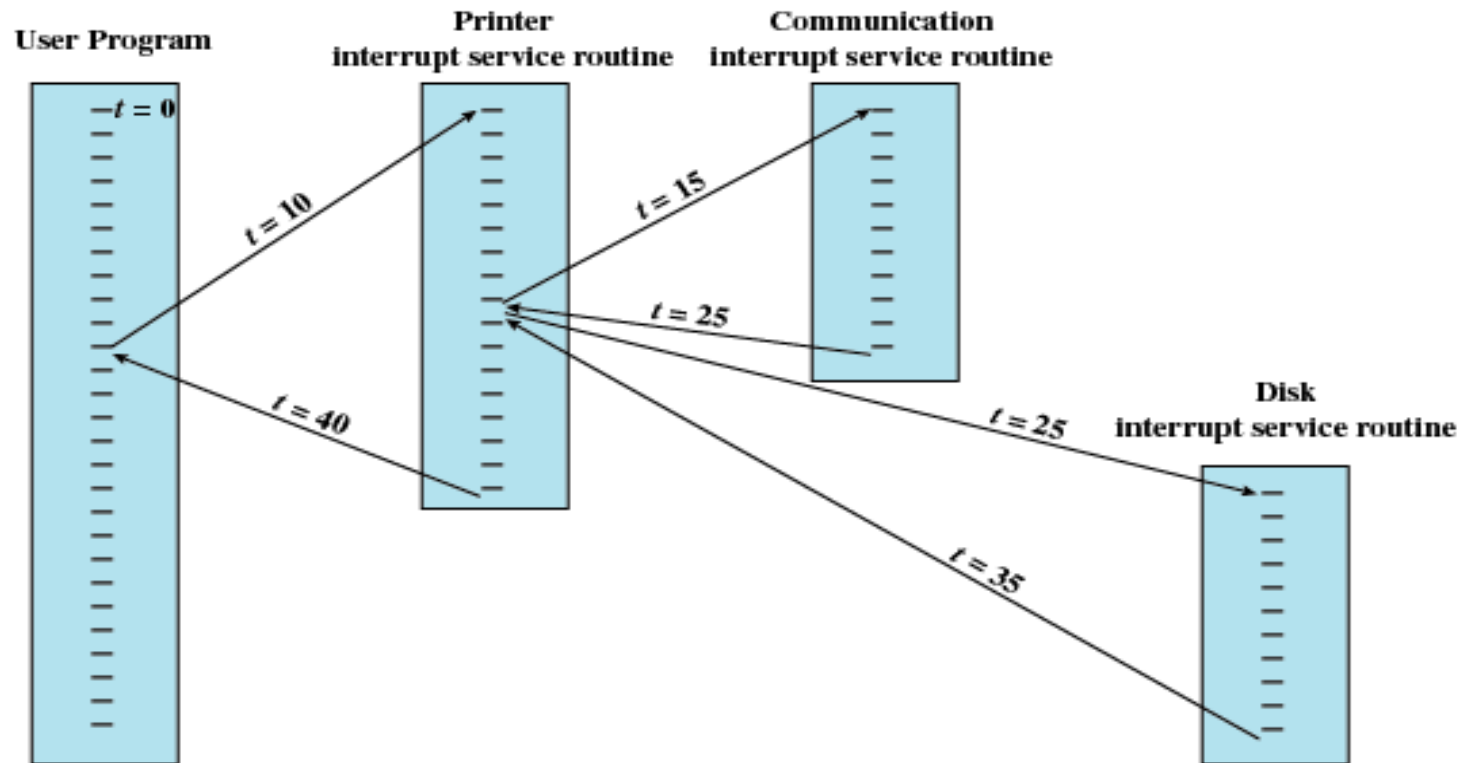


# Multiple Interrupts

- Define priorities for interrupts



# Multiple Interrupts



**Example Time Sequence of Multiple Interrupts**



# Multiprogramming

- Processor has more than one program to execute
- The sequence the programs are executed depend on their relative priority and whether they are waiting for I/O
- After an interrupt handler completes, control may not return to the program that was executing at the time of the interrupt



# Memory Hierarchy

- Faster access time, greater cost per bit
- Greater capacity, smaller cost per bit
- Greater capacity, slower access speed



# Disk Cache

- A portion of main memory used as a buffer to temporarily to hold data for the disk
- Disk writes are clustered
- Some data written out may be referenced again. The data are retrieved rapidly from the software cache instead of slowly from disk

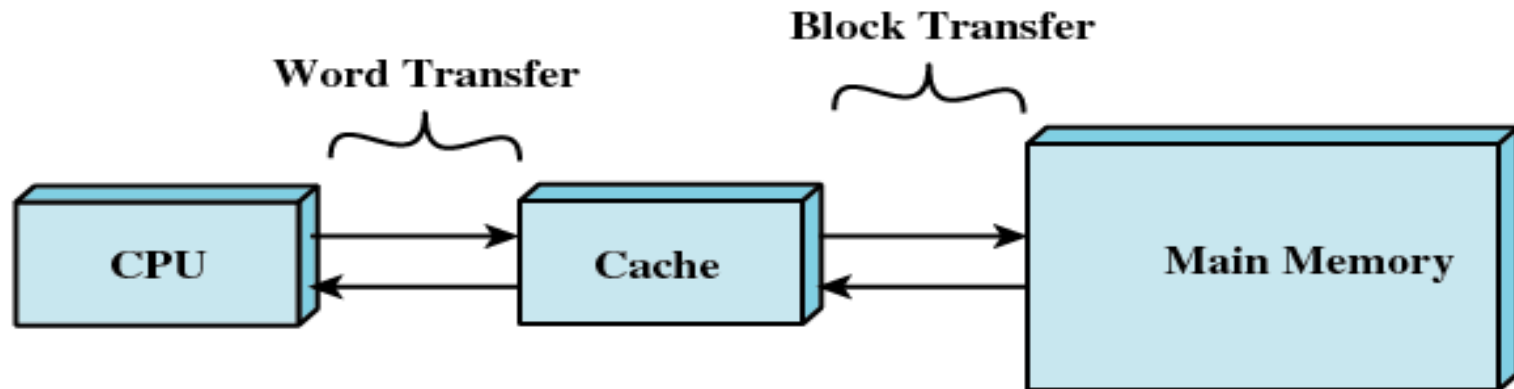


# Cache Memory

- Invisible to operating system
- Increase the speed of memory
- Processor speed is faster than memory speed
- Exploit the principle of locality



# Cache Memory



**Cache and Main Memory**



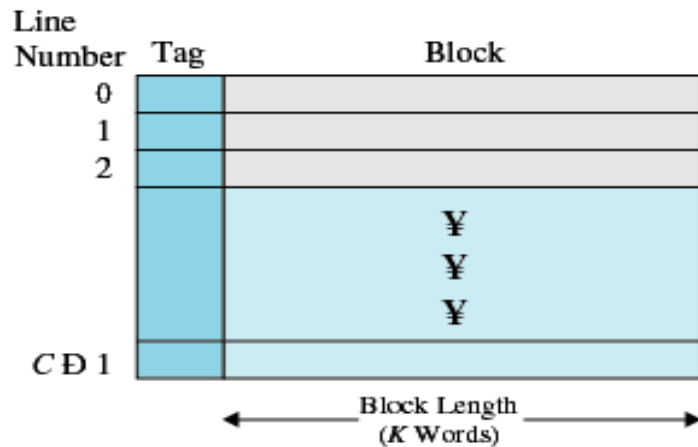
# Cache Memory

- Contains a copy of a portion of main memory
- Processor first checks cache
- If not found in cache, the block of memory containing the needed information is moved to the cache and delivered to the processor

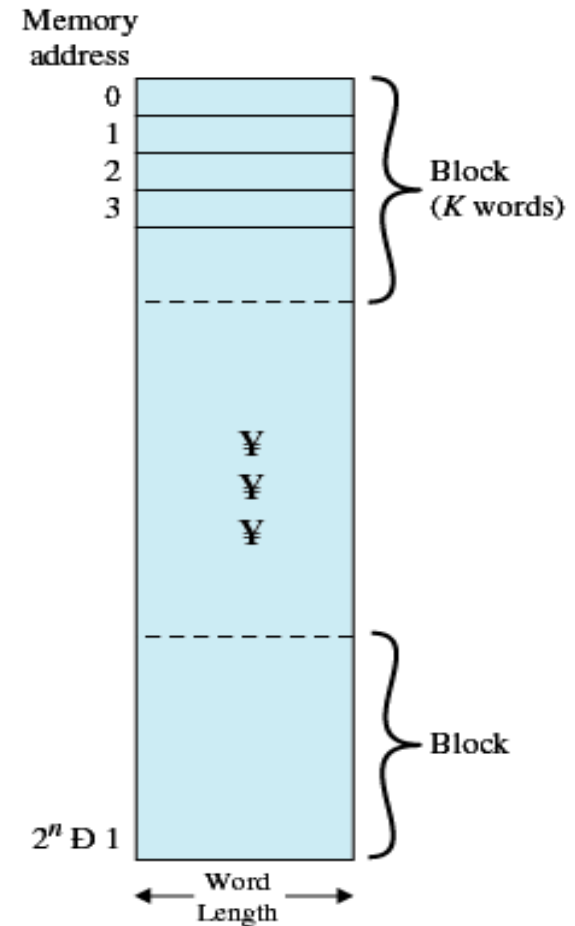




# Cache/Main Memory System



(a) Cache

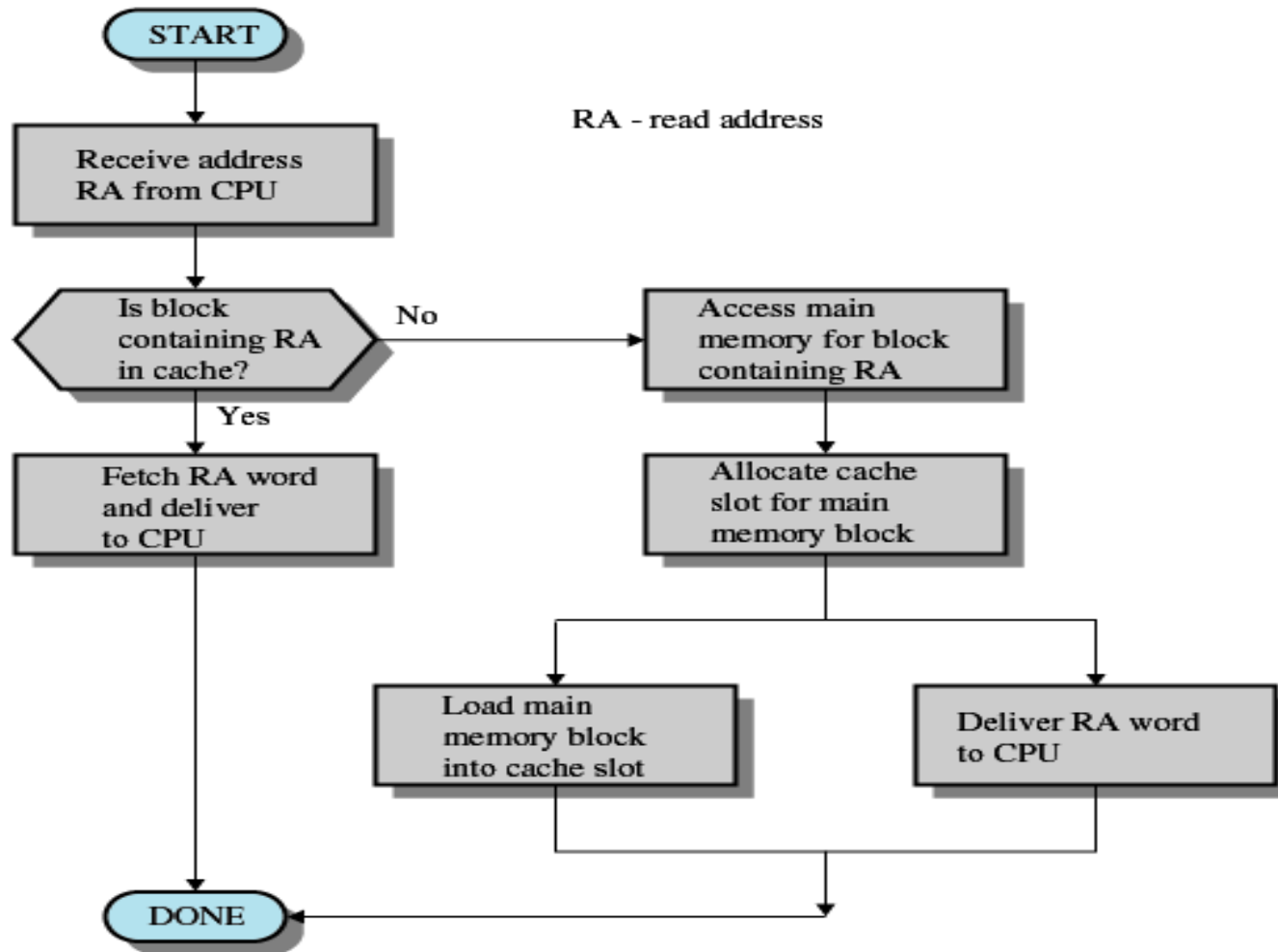


(b) Main memory

Cache/Main-Memory Structure



# Cache Read Operation



# Cache Design

- Cache size
  - Small caches have a significant impact on performance
- Block size
  - The unit of data exchanged between cache and main memory
  - Larger block size more hits until probability of using newly fetched data becomes less than the probability of reusing data that have to be moved out of cache



# Cache Design

- Mapping function
  - Determines which cache location the block will occupy
- Replacement algorithm
  - Determines which block to replace
  - Least-Recently-Used (LRU) algorithm



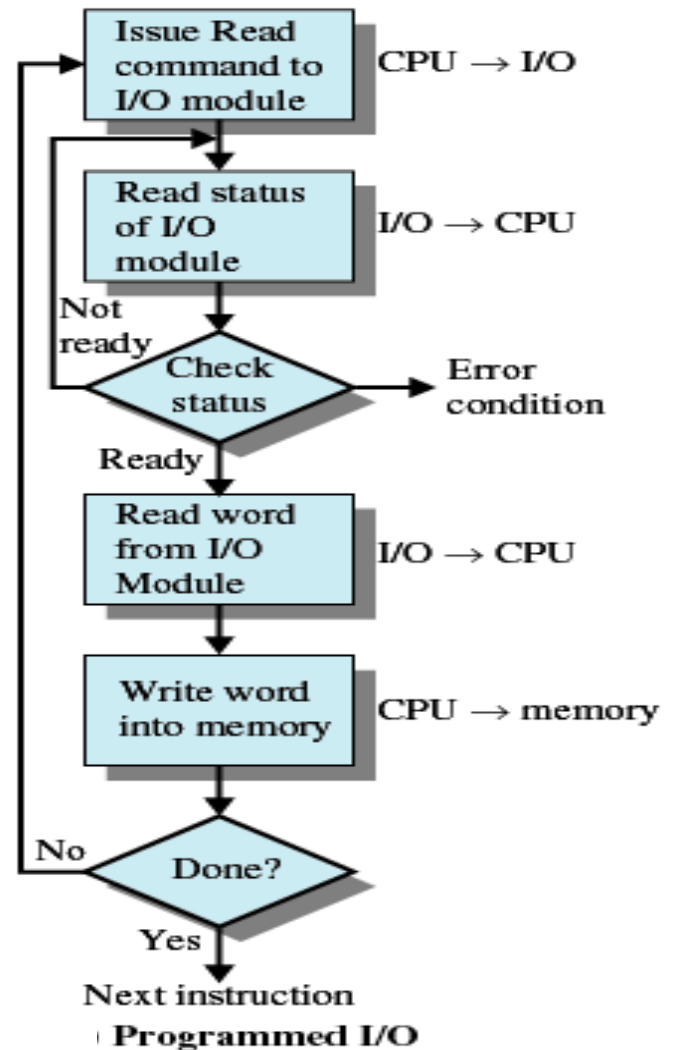
# Cache Design

- Write policy
  - When the memory write operation takes place
  - Can occur every time block is updated
  - Can occur only when block is replaced
    - Minimizes memory write operations
    - Leaves main memory in an obsolete state



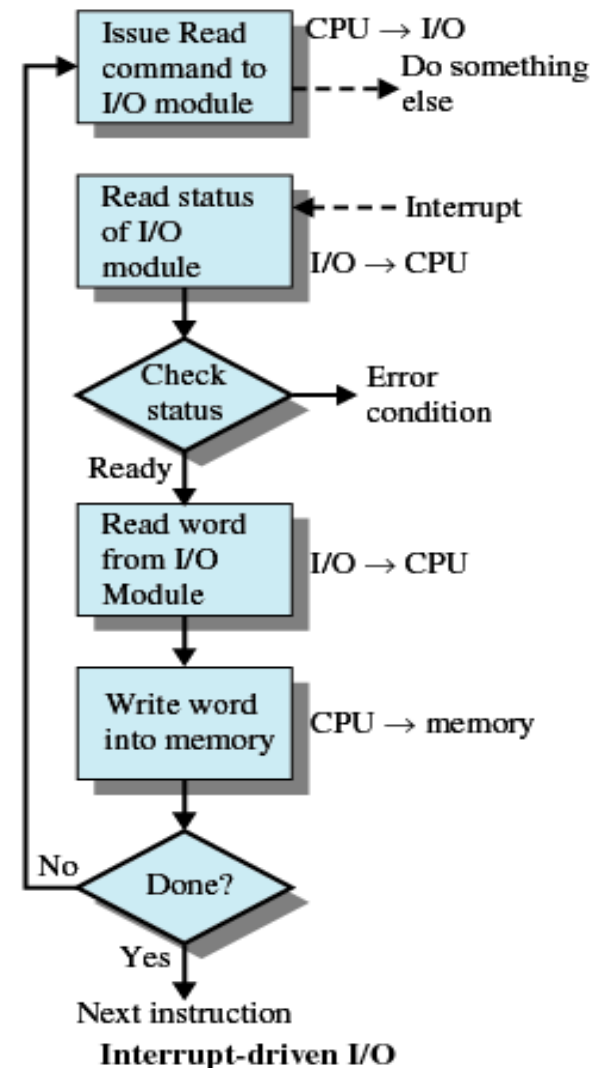
# Programmed I/O

- I/O module performs the action, not the processor
- Sets appropriate bits in the I/O status register
- No interrupts occur
- Processor checks status until operation is complete



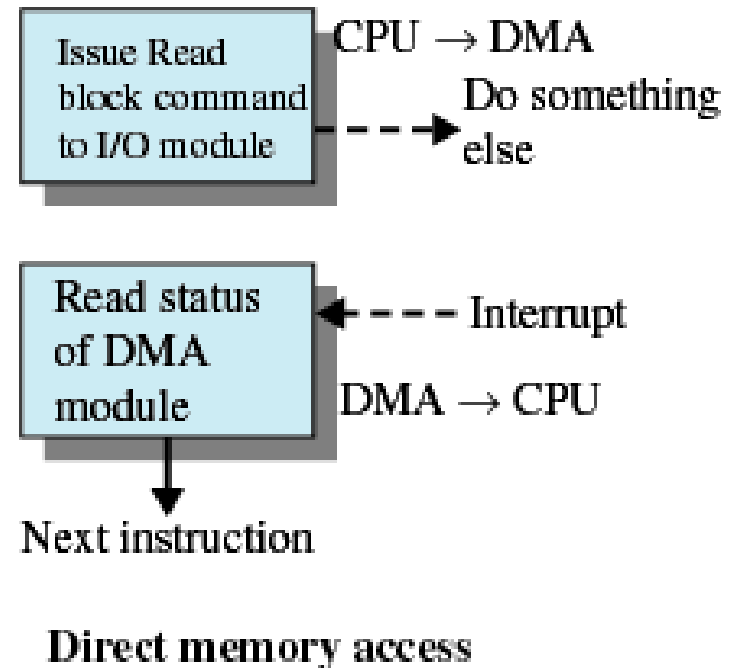
# Interrupt-Driven I/O

- Processor is interrupted when I/O module ready to exchange data
- Processor saves context of program executing and begins executing interrupt-handler
- No needless waiting
- Consumes a lot of processor time because every word read or written passes through the processor



# Direct Memory Access

- Transfers a block of data directly to or from memory
- An interrupt is sent when the transfer is complete
- Processor continues with other work





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